ENERGY FROM THE WIND



Introduction

Windmills have been used for many centuries for pumping water and milling grain. The discovery of the internal combustion engine and the development of electrical grids caused many windmills to disappear in the early part of this century. However, in recent years there has been a revival of interest in wind energy and attempts are underway all over the world to introduce cost-effective wind energy conversion systems for this renewable and environmentally benign energy source.

In developing countries, wind power can play a useful role for water supply and irrigation (windpumps) and electrical generation (wind generators). These two variants of windmill technology are discussed in separate technical briefs. This brief gives a general overview of the resource and of the technology of extracting energy from the wind.

Energy availability in the wind

The power in the wind is proportional to the cube of wind velocity. The general formula for wind power is:

Power = density of air x swept area x velocity cubed

 $= \frac{1}{2} \tilde{n} A v^3$

If the velocity (v) is in m/s, then at sea level (where the density of air is 1.2 kg/m³) the power in the wind is:

Power = $0.6 \times v^3$ Watts per m² of rotor swept area

This means that the power density in the wind will range from 10W/m² at 2.5m/s (a light breeze) to 41,000W/m² at 40m/s (a hurricane). This variability of the wind power resource strongly influences virtually all aspects of wind energy conversion systems design, construction, siting, use and economy.

The wind resource

Unfortunately, the general availability and reliability of windspeed data is extremely poor in many regions of the world. Large areas of the world appear to have mean annual windspeeds below 3m/s, and are unsuitable for wind power systems, and almost equally large areas have windspeeds in the intermediate range (3-4.5m/s) where wind power may or may not be an attractive option. In addition, significant land areas have mean annual windspeeds exceeding 4.5m/s where wind power would most certainly be economically competitive.





Principles of wind energy conversion

There are two primary physical principles by which energy can be extracted from the wind; these are through the creation of either drag or lift force (or through a combination of the two). The difference between drag and lift is illustrated (see Figure 1) by the difference between using a spinaker sail, which fills like a parachute and pulls a sailing boat with the wind, and a bermuda rig, the

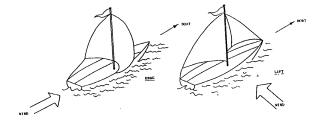


Figure 1: Drag and Lift Forces

familiar triangular sail which deflects with wind and allows a sailing boat to travel across the wind or slightly into the wind. Drag forces provide the most obvious means of propulsion, these being the forces felt by a person (or object) exposed to the wind. Lift forces are the most efficient means of propulsion but being more subtle than drag forces are not so well understood.

The basic features that characterise lift and drag are:

- drag is in the direction of airflow
- lift is perpendicular to the direction of airflow
- generation of lift always causes a certain amount of drag to be developed
- with a good aerofoil, the lift produced can be more than thirty times greater than the drag
- lift devices are generally more efficient than drag devices

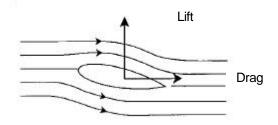


Figure 2: Aerofoil

Types and characteristics of windmill rotors

There are two main families of windmills: vertical axis machines and horizontal axis machines. These can in turn use either lift or drag forces to harness the wind. Of these types the horizontal axis lift device represents the vast majority of successful wind machines, either ancient or modern. In fact other than a few experimental machines virtually all windmills come under this category.

There are several technical parameters that are used to characterise windmill rotors. The **tip-speed ratio** is defined as the ratio of the speed of the extremities of a windmill rotor to the speed of the free wind. It is a measure of the 'gearing ratio' of the rotor. Drag devices always have tip-speed ratios less than one and hence turn slowly, whereas lift devices can have high tip-speed ratios and hence turn quickly relative to the wind.

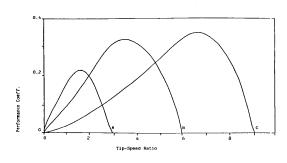


Figure 3: Tip speed ratio and the performance coefficient

The proportion of the power in the wind that the rotor can extract is termed the **coefficient of performance** (or power coefficient or efficiency; symbol C_p) and its variation as a function of tip-speed ratio is commonly used to characterise different types of rotor. It is physically impossible to extract all the energy from the wind, without bringing the air behind the rotor to a standstill.



Consequently there is a maximum value of C_p of 59.3% (known as the Betz limit), although in practice real wind rotors have maximum C_p values in the range of 25%-45%.

Solidity is usually defined as the percentage of the circumference of the rotor which contains material rather than air. Highsolidity machines carry a lot of material and have coarse blade angles. They generate much higher starting torque than low-solidity machines but are inherently less efficient than low-solidity machines as shown in Figure 4. The extra materials also cost more

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money. However, low-solidity machines need to be made with more precision which leads to little difference in costs.

Figure 4: Solidity and Torque

The choice of rotor is dictated largely by the characteristic of the load and hence of the end use. These aspects are discussed separately in the technical briefs on windpumps and windgenerators. Table 1 compares different rotor types.

Туре	Speed	Torque	Manufacture	C_p	Solidity %
Horizontal Axis					
Cretan sail	Low	Medium	Simple	.0515	50
Cambered plate fan	Low	High	Moderate	.1530	50-80
Moderate speed aero- generator	Moderate	Low	Moderate	.2035	5-10
High speed aero-generator	High	Very low	Precise	.3045	< 5
Vertical Axis					
Panemone	Low	Medium	Crude	> .10	50
Savonius	Moderate	Medium	Moderate	.15	100
Darrieus	Moderate	Very low	Precise	.2535	10-20
Variable Geometry	Moderate	Very low	Precise	.2035	15-40

Table 1: Comparison of rotor types

Windmill performance

Although the power available is proportional to the cube of windspeed, the power output has a lower order dependence on windspeed. This is because the overall efficiency of the windmill (the product of rotor C_p , transmission efficiency and pump or generator efficiency) changes with windspeed. There are four important characteristic windspeeds:

- the cut-in windspeed: when the machine begins to produce power
- the design windspeed: when the windmill reaches its maximum efficiency
- the rated windspeed: when the machine reaches its maximum output power
- the furling windspeed: when the machine furls to prevent damage at high windspeeds.



Performance data for windmills can be misleading because they may refer to the peak efficiency (at design windspeed) or the peak power output (at the rated windspeed). The data could also refer to the average output over a time period (e.g. a day or a month).

Because the power output varies with windspeed, the average output over a time period is dependent in the local variation in windspeed from hour to hour. Hence to predict the output for a given windmill one needs to have output characteristics of the windmill and the windspeed distribution curve of the site (duration at various windspeeds). Multiplying the values of both graphs for each windspeed interval and adding all the products gives the total energy output of that windmill at that site.

References and Further Reading

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